







Exploring Analytic Geometry with Mathematica (Vossler) (1).pdf - Adobe Reader  
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### Collinear Points

In a previous chapter it was demonstrated that the three points  $P_1(x_1, y_1)$ ,  $P_2(x_2, y_2)$  and  $P_3(x_3, y_3)$  are collinear if their coordinates satisfy the determinant equation

$$\begin{vmatrix} x_1 & y_1 & 1 \\ x_2 & y_2 & 1 \\ x_3 & y_3 & 1 \end{vmatrix} = 0.$$

This condition may be stated in a more intuitive form using the two-point form of a line. The line defined by  $P_1$  and  $P_2$  must be satisfied by  $P_3$  yielding the condition

$$-(y_2 - y_1)x_3 + (x_2 - x_1)y_3 + x_1y_2 - x_2y_1 = 0$$

which can be put into the more symmetrical form

$$y_1(x_2 - x_3) + y_2(x_3 - x_1) + y_3(x_1 - x_2) = 0.$$

### 5.5 Point-Slope Form

Since  $m = \frac{y_2 - y_1}{x_2 - x_1}$ , the two-point form of a line can be reduced to the *point-slope form*

$$y - y_1 = m(x - x_1)$$

as shown in Figure 5.3. In general form the equation of the line is

$$mx - y + (y_1 - mx_1) = 0.$$

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