

АВТОМАТИКА ЭЛЕМЕНТЛАРИНИНГ СТАТИК ТАВСИФНОМАЛАРИНИ АНИҚЛАШ

ИНДУКТИВ ДАТЧИК МИСОЛИДА

Datchiklar bir hildagi bir necha
asosiy ko'rsatkichlarga ega:

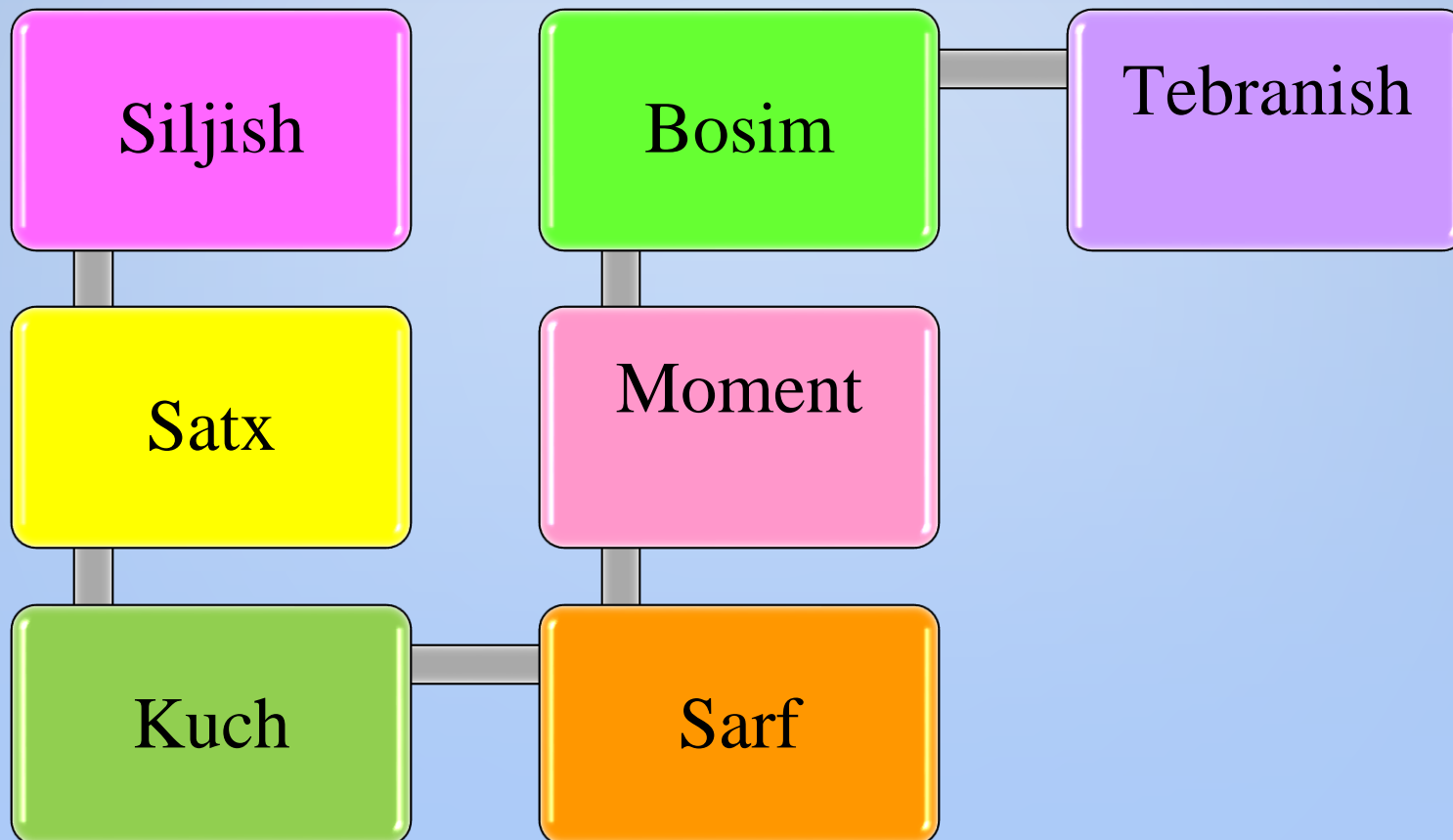
Statik tavsifnomasi

dinamik tavsifnomasi

absolyut xatolig

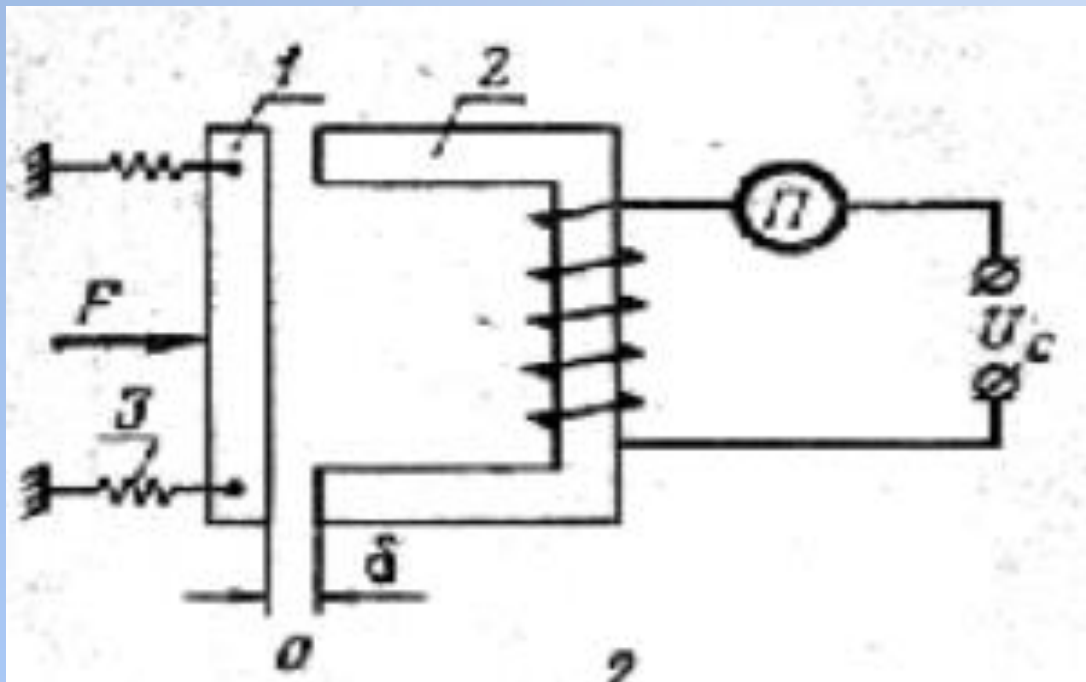
nisbiy xatolig

INDUKTIV DATCHIKLAR NAZORAT QILADIGAN KATTALIKLAR



INDUKTIV DATCHIKNING PRINSPIALSXEMASI

PARAMETRLARNI O'ZGARTIRISH KETMA-KETLIGI



$$F \rightarrow \delta_B \rightarrow R_M \rightarrow L \rightarrow X_L \rightarrow Z \rightarrow I,$$

Bu erda: F - kuch;

δ_v - xavo bo'shlig'i uzunligi;

R_m - magnit qarshilik;

L - induktivlik;

X_L - induktiv qarshilik;

Z - to'la qarshilik;

I - tok.

2) DATCHIK INDUKTIVLIGI QUIYIDAGI FORMULA ORQALI ANIQLANADI:

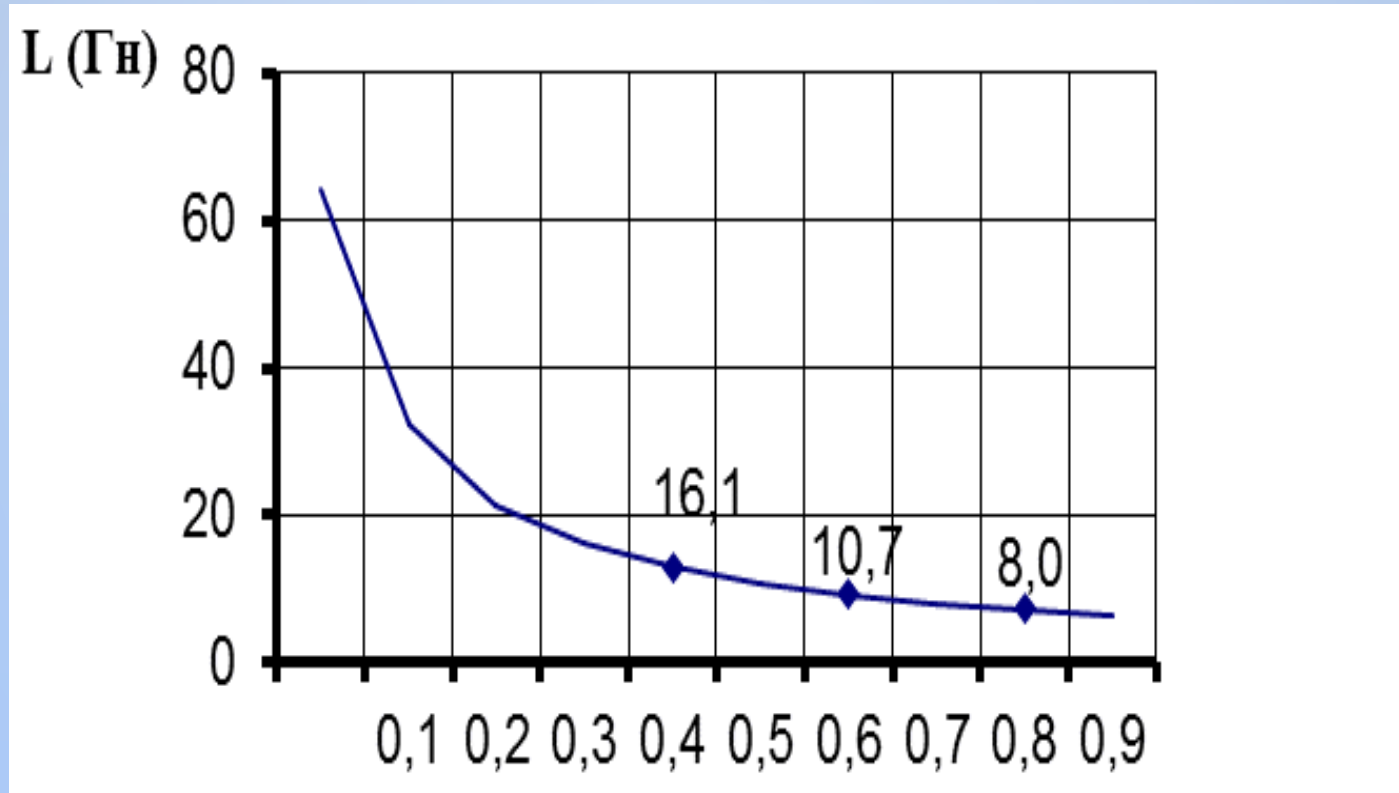
$$L = \left(2/\delta_B\right)\pi * n^2 * S_M * 10^{-7}$$

δ_v – Xavo bo'shlig'i uzunligi;

n – o'ramlar soni;

S_m – o'tkazgich kesim yuzasi.

STATIK TAVSIFNOMA $L = F(\delta V)$



KELTIRILGAN MA'LUMOTLAR ASOSIDA INDUKTIV DATCHIKNING INDUKTIVLIGINING BO'SHLIG'I UZUNLIGIGA BOG'LIQLIGINI ANIQLANG

$$\delta_{v1} = 0,4 \text{ mm};$$

$$\delta_{v2} = 0,6 \text{ mm};$$

$$\delta_{v3} = 0,8 \text{ mm};$$

$$S_m = 40 \text{ mm}^2;$$

$$n = 16000 \text{ o'ram.}$$