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VA RIVOJLANISH ISTIQBOLLARI”**

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IMPROVING THE CONTROL AND CONTROL OF THE ENERGY- SUPPLIED ASYNCHRONOUS MOTOR REACTIVE POWER CONSUMPTION THAT SOLAR PANELS ARE DEVELOPING

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Annotation: in the world, solar energy sources are widely used in the continuous and high-quality supply of consumer electricity needs in this regard, large-scale work is being carried out in the energy system in our country, including increasing the quality indicators of electricity developing the most common asynchronous motors solar panels in the industry, increasing the efficiency of asynchronous motors.

Keywords: solar power supply, insulation cline, magnetic core, sator pins, electromagnetic current Switch.

In this regard, 70-80% of the consumer of electricity, in which the use of electricity developing solar panels has become popular in providing consumers with uninterrupted electricity, providing asynchronous motors with uninterrupted and high-quality electricity, through the asynchronous motor confidence in reducing the reactive power wastes consumed, the use of accurate, fast, compact and cost-effective electromagnetic current switches is a pressing issue. Due to the fact that the magnetic core of existing current transformers used in the control and control of large-scale asynchronous motor reactive power consumption of industrial production and the national economy is a ballad of the economic cost of large size, asynchronous motor cannot provide fiber information about the waste of stator currents in control. In the control and control of reactive power consumption in asynchronous motors supplied from a solar power source, the use of electromagnetic current switches placed between asynchronous motor stator wedge and the consistency Cline is the most preferred methods when measuring the scattering magnetic flux occurring in an asynchronous motor stator with high precision. Single-spoke asynchronous motors supplied from a single-phase source account for 30% of the total used motors when industrial production, folk hooliganism, and the maishiy consumer feel the devices added.

In obtaining the results of the research experiment, there is an existing BH-0.66/30 II, which is widely used today, with classical current transformers of type and asynchronous motor stator clamp and transverse cross-sectional surface placed between the isalation Cline $S=0.25$ mm, li current Switch rings are placed between DOL-34H type asynchronous motor sataor wedge and the isalation Cline asynchronous motor power $P=550W$, $C=18$ mF, working capacitor Battery $C=10$ mF, stator current $I=4.1$ A, voltage $U=220$ V, frequency $Hz=50$ Hz, $\eta_n=0.60\%$, Asynchronous motor with $T=1350$ ayl/min control and control of reactive power consumption in control and control of reactive power consumption, research the results were presented in Table 1, yellow (-)- electromagnetic current Switch output voltage red (-)- classical current transormator output voltage characteristic, research experiments, dynamic descriptions Prek-TECH-12/65. 2023.

$$\delta = \frac{U_{curre.trans} - U_{electromagnetic curr.transf.}}{U_{electromagnetic cu.transf.}} 100\% \quad 1)$$

The electromagnetic current transducer as well as the chiqsh characteristics of classical current transformers were calculated through the expression presented above in comparative comparative comparative analysis. Dynamic time dependence descriptions of research results obtained in oscillograms are shown in Table 1.

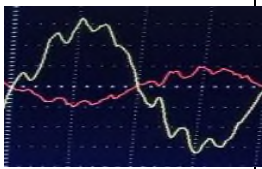
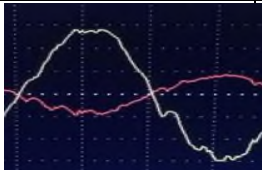
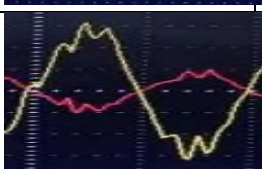
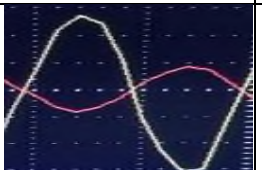
№	Connection scheme status	Oscillogram appearance	Nonsinusoidal coefficient THD _{nosinus.} [%]	Voltage at the output of the electromagnetic current converter U _{exit} [V]	Amount of current flowing from inductive and capacitive elements I [A]
1.	An induction motor is connected to the grid only through a phase-shifting capacitor bank		Asynchronous motor in load mode THD = 6,4	U _{exit} =3,04	I=0,91 I _{C1} =0,97
2.	An asynchronous motor is connected to the network through a phase-shifting inductive coil and a working capacitor battery		Asynchronous motor in load mode THD = 6.01	U _{exit} =3,11	I=0,81 I _{C1} =1,04 I _L =0,30
3.	Asynchronous motor starting and connected to the network through the working capacitor battery		Asynchronous motor in load mode THD = 5,8%	U _{exit} =4,1	I=1,03 I _{C1} =0,78 I _{C2} =0,38
4.	Asynchronous motor phase shifter through inductive start and working capacitor battery		Asynchronous motor in load mode THD = 4,5%	U _{exit} =4,3	I=1,01 I _{C1} =0,75 I _{C2} =0,36 I _L =0,22

Table 1.

From the research experience, it can be concluded that the nosinusoidality indicators of high harmonic currents obtained from the electromagnetic current reciprocator compared to the existing classical current transformer were determined to be accurate to $\Delta=6.1\%$.

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165	Phase composition of ceramic magnetic materials synthesized in a solar furnace. J.Z. Sheramatov O.T. Rajamatov M.S. Payzullakhanov M.H. Aripova	360
166	Особенности выходных нагрузочных характеристик солнечных фотоэлектрических модулей на основе полупроводникового перовскита. Р.Р. Кабулов Л.У. Шухратова Л.У. Шухратова Ф. Касимов Д.С. Саранин Ш.М. Худайбердиев Ш.Ш. Шосаитов	362
167	Preparation and stability of nanofluids. D.Jalilov, T.Juraev, A.Halimov, J.Axatov	364
168	Shamol generatorlarini samaradorligini oshirish. A.Axmadjonov, A. Botirjonov, N.Jamoliddinov, A.Nabiyev	366
169	История и современные тенденции солнечных коллекторов. Б.Мирзамахмудов	368
170	Improving the control and control of the energy-supplied asynchronous motor reactive power consumption that solar panels are developing. Siddikov I. X Azamov S. S	370
171	Perovskite asosli lateral geterostrukturali quyosh elementini modellashtirish. I.G'ulomova, R.Aliyev	372
172	Возобновляемые источники энергии и экологическая устойчивость. А.Р. Кадиров, Х.З. Ботиров, Ж.Р. Пармонов, Ш.Ш. Бурунов	374
173	Ikki tomonlama sezgir quyosh elementi uchun nur qaytarishga qarshi qatlam hosil qilish orqali uning fotoelektrik parametrlarini aniqlash. R.Aliyev, M.M.Komilov, N.A.Mirzaalimov, Sh.B.Muhtorov, B.D.Rashidov, R.B.Rahmatullayev, F.A.Mamatkarimova	376
174	Shahar ko'chalari uchun gibrid quyosh-shamol mikro-energetik qutilmasi. R.Aliyev, N.A.Mirzaalimov, B.D.Rashidov, A.A.Mirzaalimov, M.M.Komilov, T.B.Abdulazizov, F.A.Mamatkarimova	378
175	O'zbekistonda quyosh panellaridan foydalanish muammolari, yechimlari va istiqbollari. Jalalov R.M, Maxmudov U.R.	380
176	Analysis of air and water cooling of photovoltaic bataries. Sh.N.Abilfayziev	382
177	Kremniy asosli quyosh eleemtalrini pyhton dasturi orqali p-n kontakt hosil qilish. R.Raxmatullayev	384
178	Shaffoflik va samaradorlikni oshiruvchi yangi materiallar. Sh.Muhtorov, E.Sultonov	386
179	Qayta tiklanuvchi energiya manbalarining hozirgi kundagi ahamiyati. Z.T.Yunusova	388
180	Quyosh elementlarida zaryad tashuvchilarning harakatchanligini haroratga bog'lanishi. Zaxidov I.O, Ismanova O.T, Azimova Sh.A, Rustamova K.Q, Axmadjonova M.F, Maxmudov U.R.	390
181	Тонкопленочный солнечный элемент на основе пленок твердого раствора $Sb_2(S_xSe_{1-x})_3$. Т.М. Разыков, К.М. Кучкаров, Р.Т. Йулдошов, Д.З. Исаков, М.А. Махмудов, Р.Р. Хуррамов, Ж.Ф. Бекмирзаев, М.П. Примматов.	392
182	Obtaining «nitron» based nanofibres with electrically conductive properties. N.Khodjaeva, I.Khudoyberdiyev, M.Makhkamov	395
183	Исследования Процесса Рассеяния Ионов С Поверхности CdTe(001) У.О.Кутлиев, Ш.П. М.У.Отабаев, С.А.Атажанова	397
184	Crystal Structure and Hirshfeld Surface Analysis of 1H-1,2,3 Triazole-Copper Complex. M.O. HakimovI, I.S. Ortikov, T.A. Sattarov, A.G.Tojiboev	399
185	LSCO/SCO O'tapanjara O'tao'tkazuvchanlik Kritik Harorati Haqida S.M. Otajonov, B.Ya. Yavidov	401
186	Изучение Вольтамперных Характеристик Системы Ni/PdSi/Si. Д.А. Ташмухамедова, Б.Е. Умирзаков, Х.Э. Абдиев, С.Т. Гулямова, С.С. Пак, Ш.Курбонов	403
187	Компьютерное Моделирование Процесса Рассеяния Ионов с Дефектной Поверхностью InGaP(001). У.О. Кутлиев, Ш.П.М.У.Отабаев, С.А. Атажанова	405
188	Pre-Nucleation Insights: Nickel's Impact on The Aggregation of Non-Planar Perylene Derivatives. D. Husanova ¹ , K. Mehmonov ² , S. Mirzaev ³ and U. Khalilov	407
189	Permeation Dynamics of CO₂, H₂S, and CH₄ in BMIMTCM Ionic Liquid: a Molecular	409